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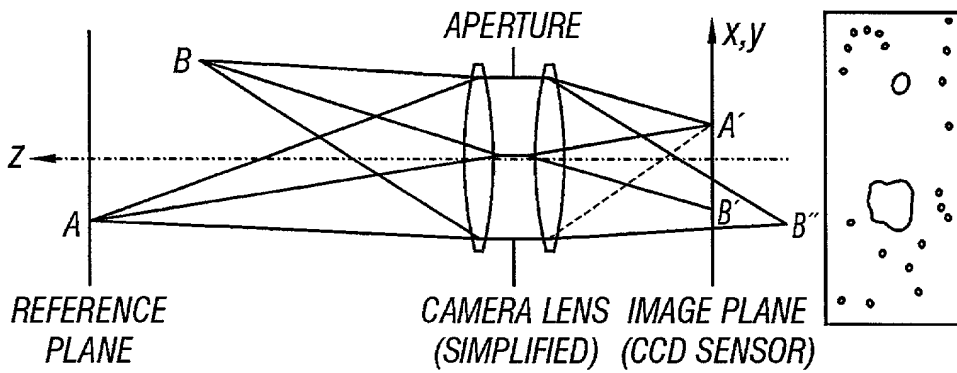


FIG. 1A

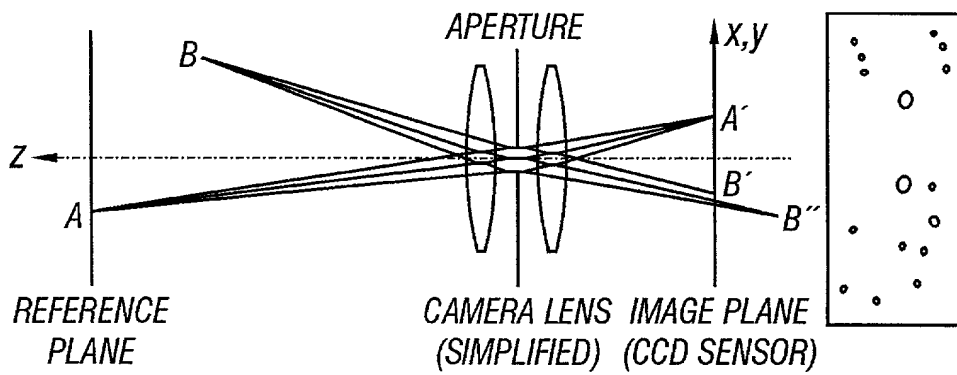


FIG. 1B

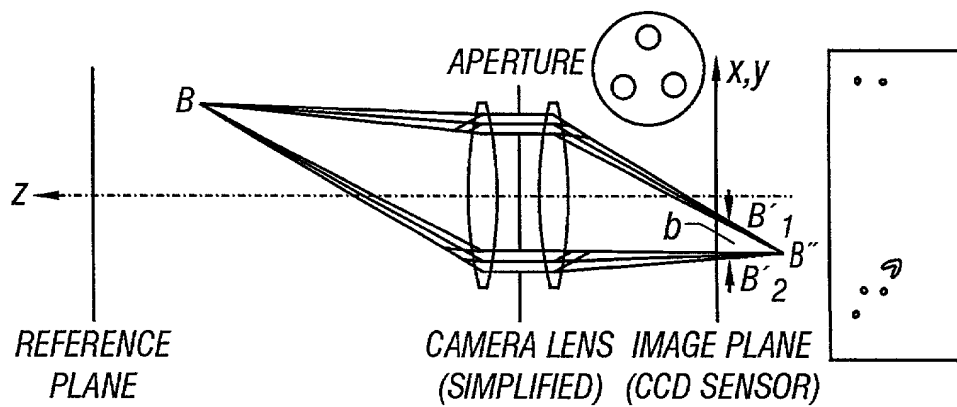


FIG. 1C

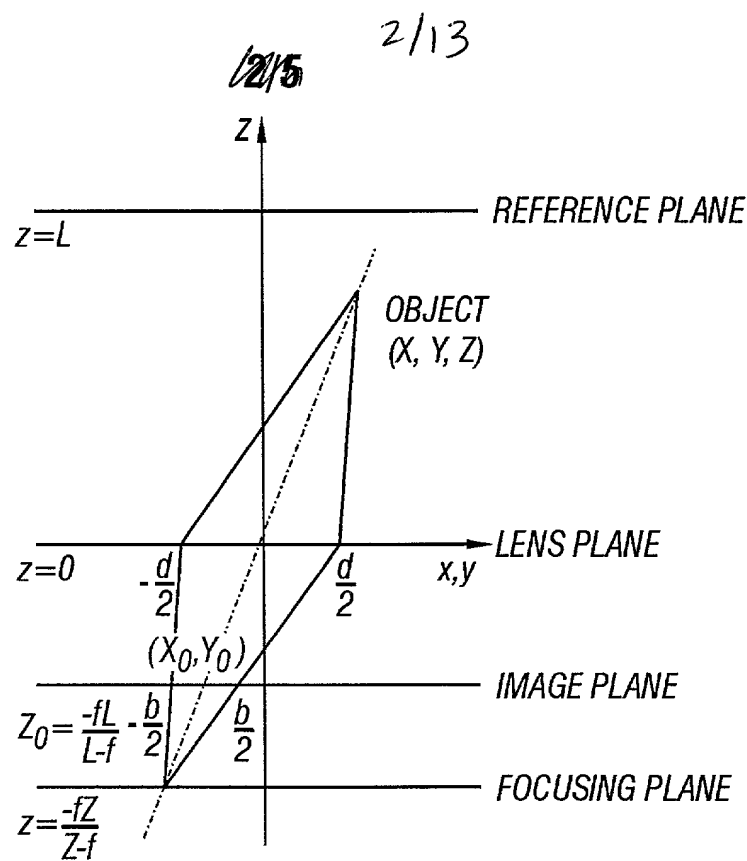


FIG. 2

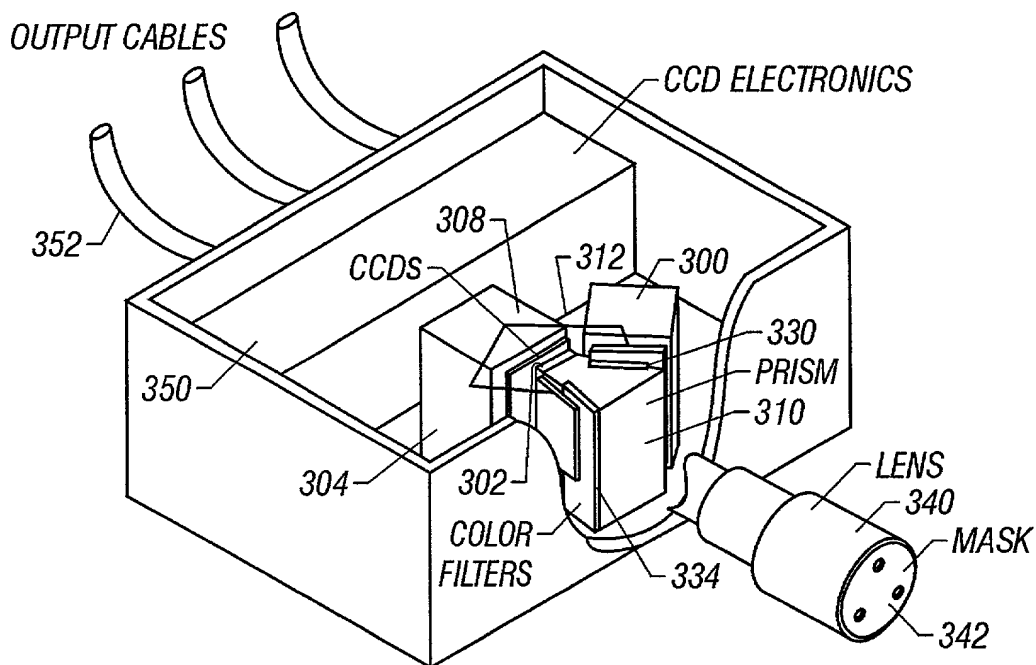


FIG. 3

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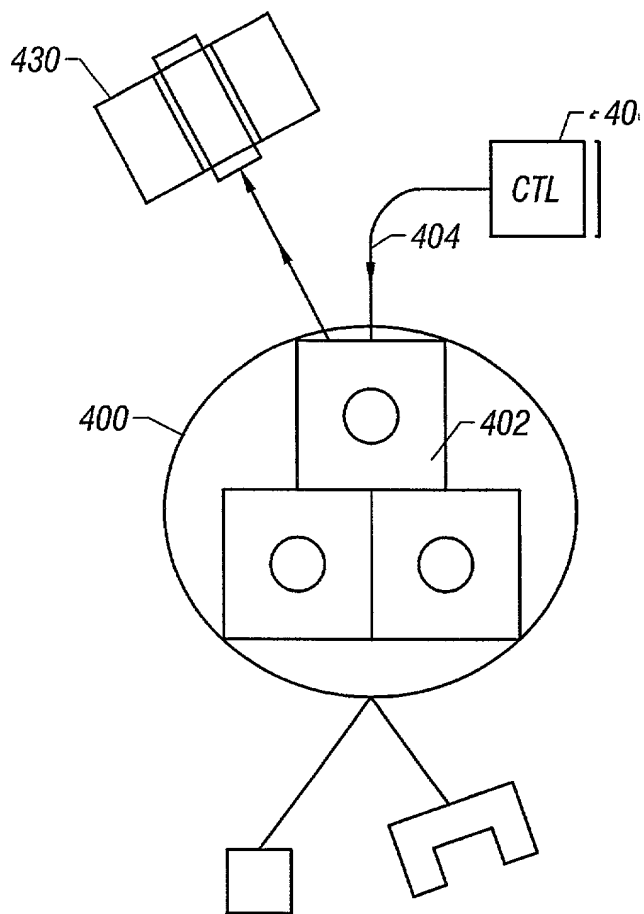


FIG. 4A

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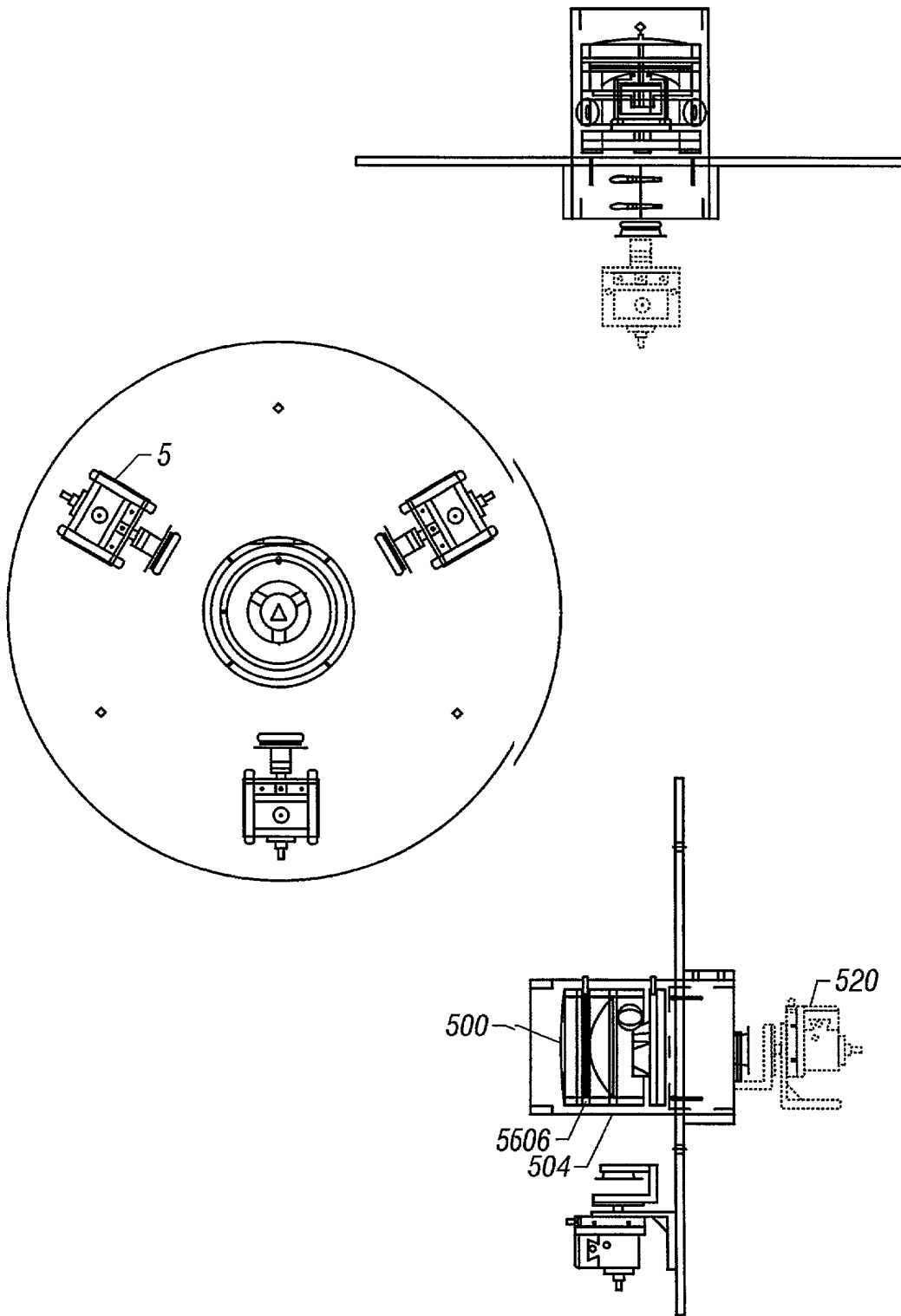


FIG. 5

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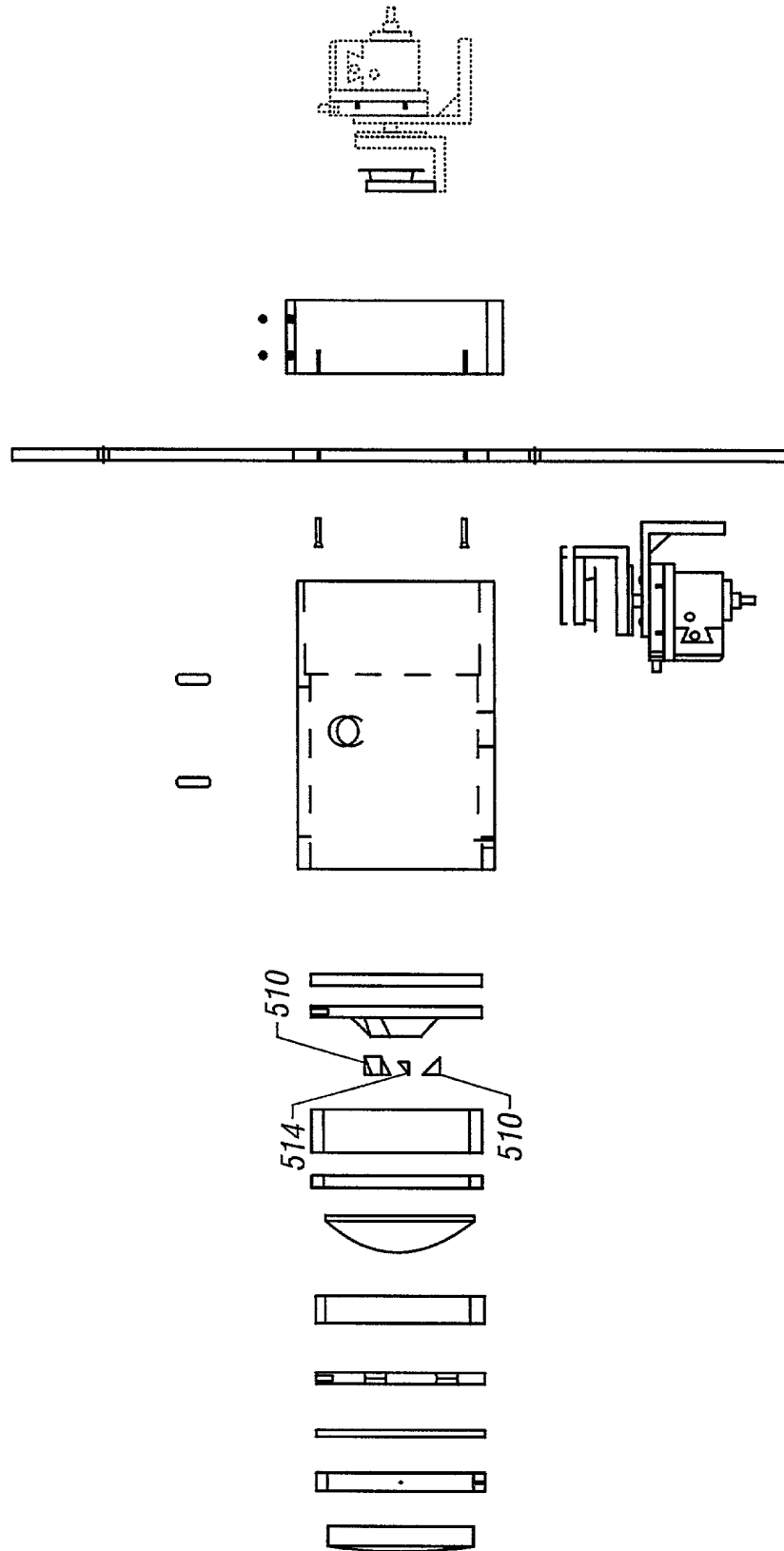


FIG. 6

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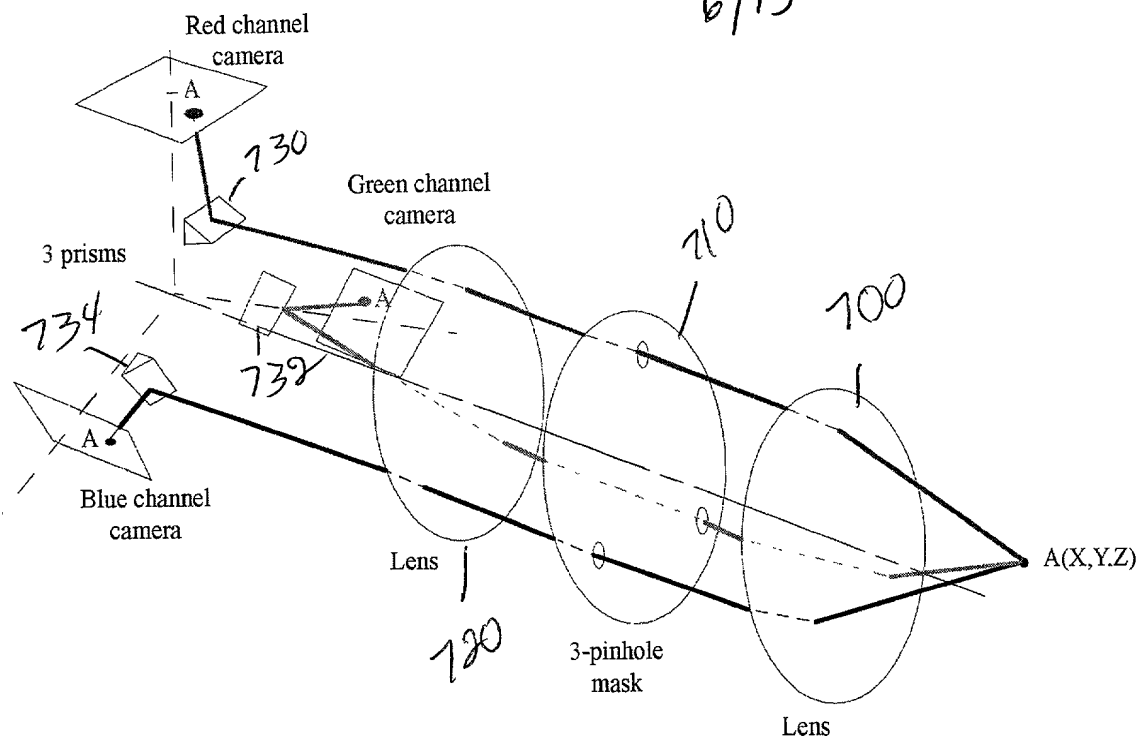


FIG 7

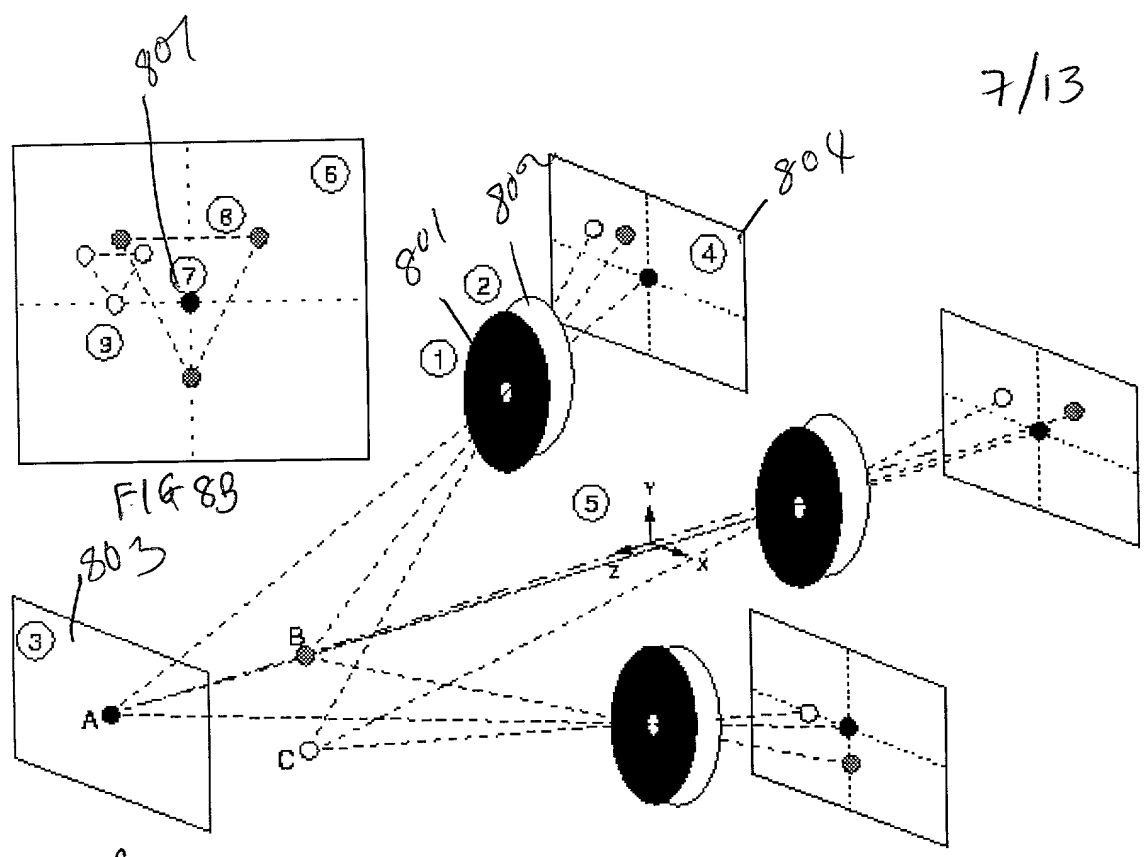


FIG 8A

FIG 8A is a perspective view of a multi-view projection system. The system includes three cameras (801, 802, 804) and three image planes (803, 805, 806). The cameras are positioned at different angles relative to the image planes. The image planes are shown as rectangles with dashed lines representing projection paths. A coordinate system (X, Y, Z) is shown near the center of the image planes. Points A, B, and C are marked on the image planes. The diagram illustrates how points in a 3D space are projected onto the 2D image planes by the cameras. Dashed lines connect the cameras to the points on the image planes, illustrating the projection geometry.

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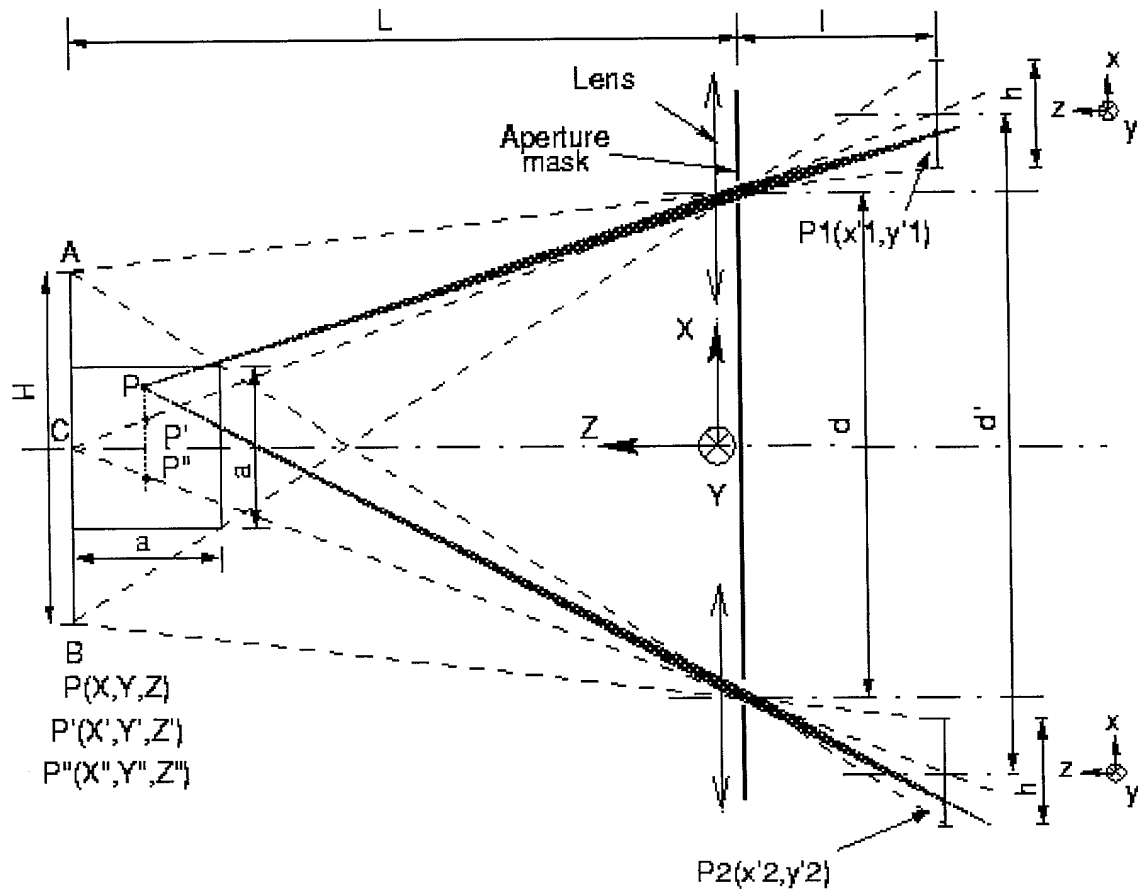
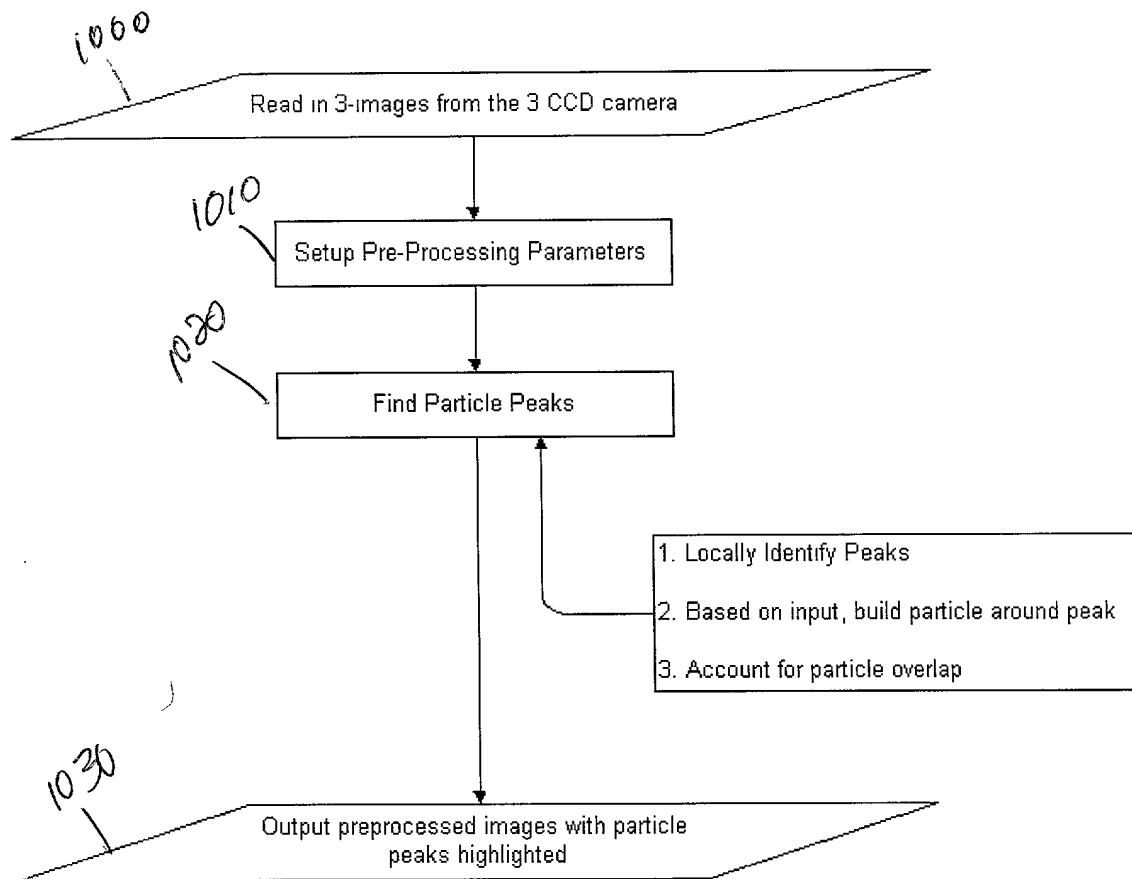


FIG 9

Program 1: DE2PIV

**FIG 10**

Program 2: FINDPART

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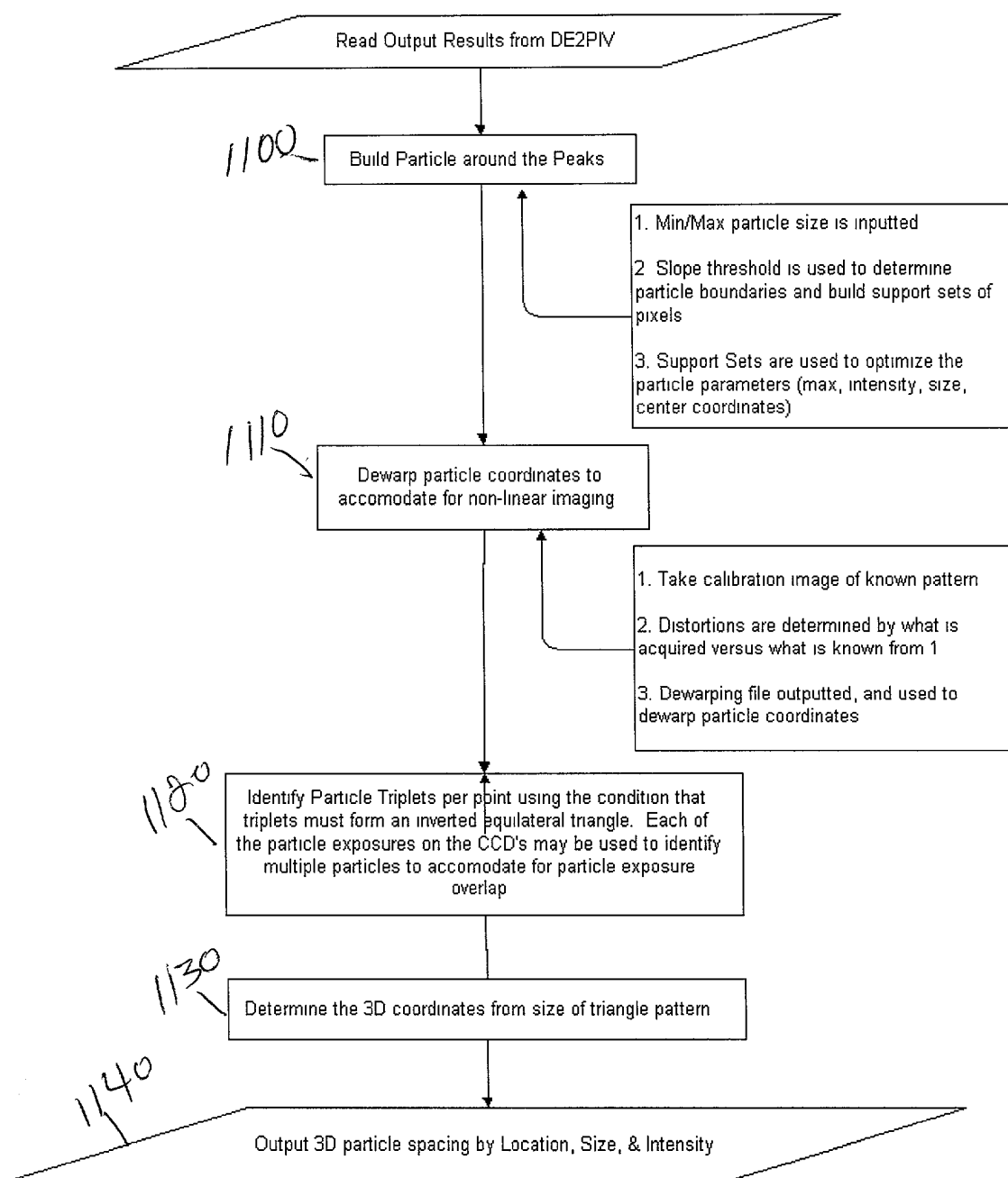


FIG 11

Program 3: FILTERPART

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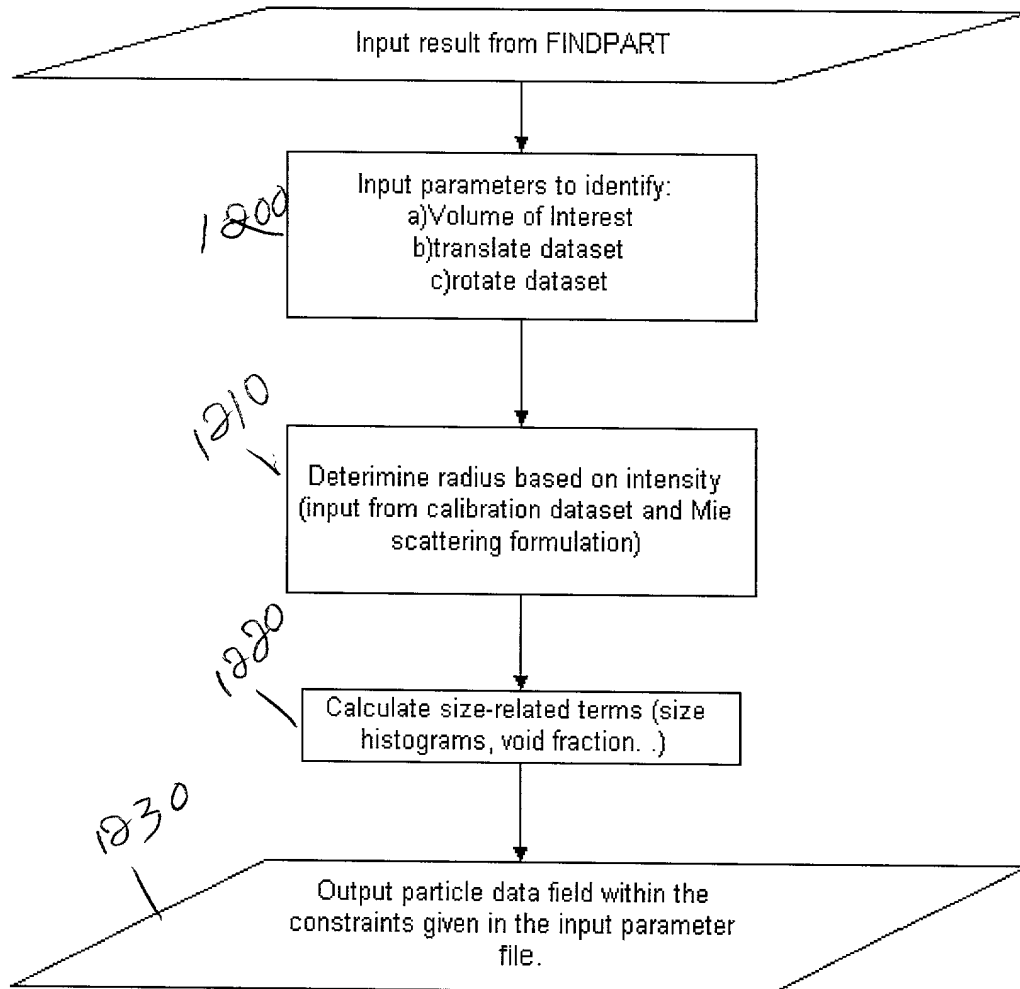


FIG 12

Program 4: FINDFLOW

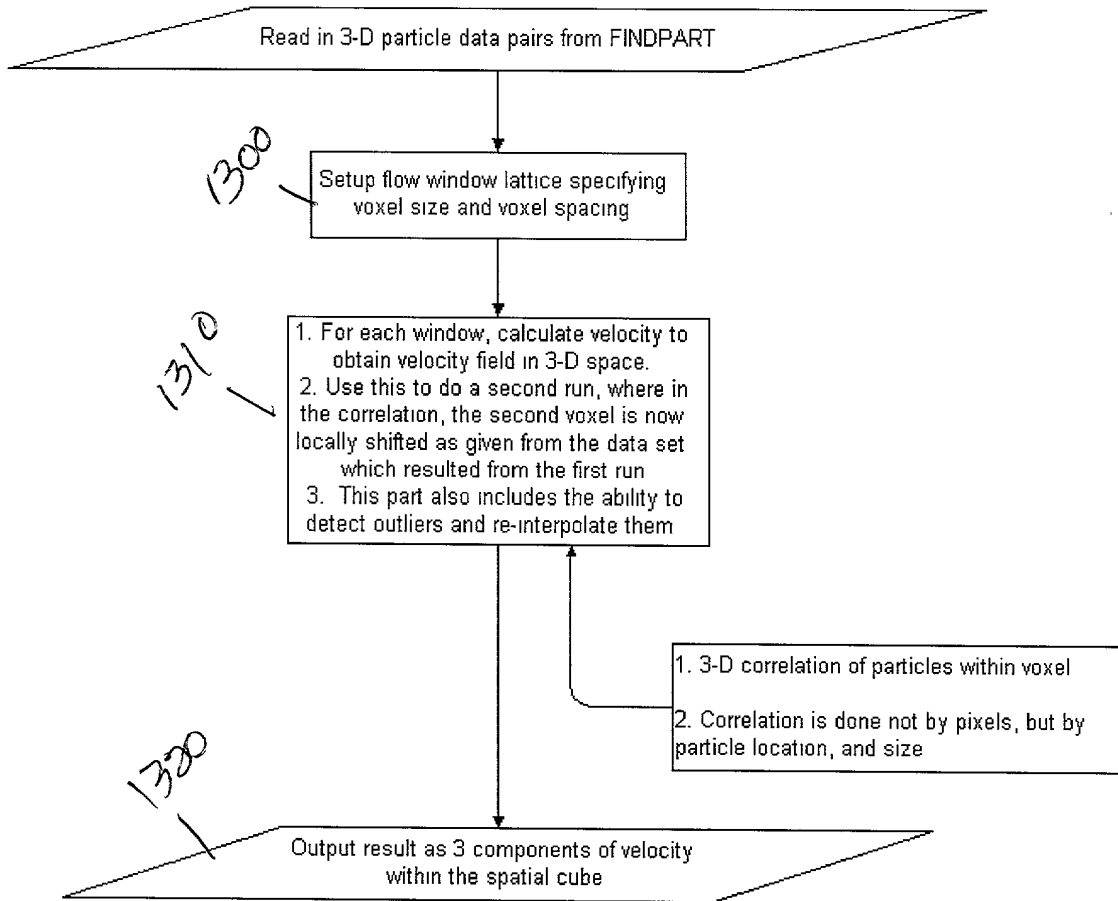


FIG 13

Program 5: FILTERFLOW

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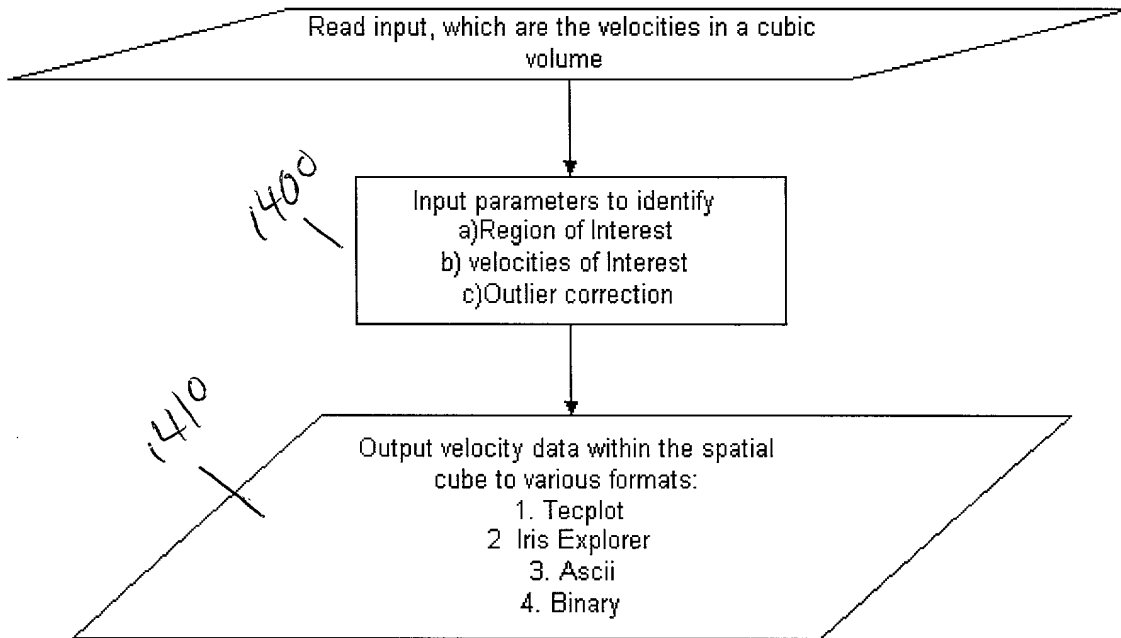


FIG 14